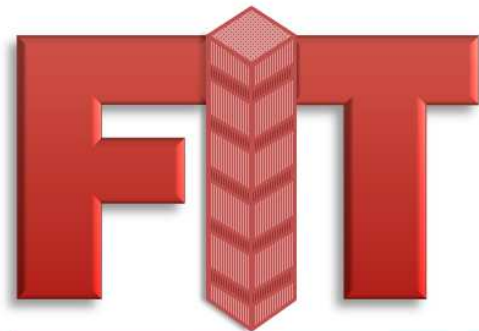




AREVA

forward-looking energy



FUELS INTEGRATED TRAINING

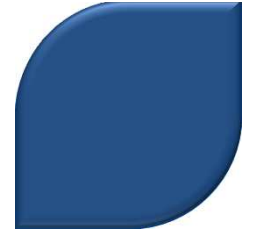
Module

2



Basic Statistics Refresher





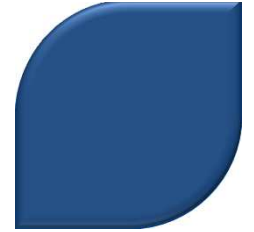
▶ **INTRODUCTION**

▶ **NORMAL DISTRIBUTION**

▶ **TOLERANCE INTERVALS**

▶ **RESPONSE SURFACE MODELS**

Learning Objectives



▶ Introduction

- ◆ Describe the difference between a bias and a random uncertainty

▶ Normal Distribution

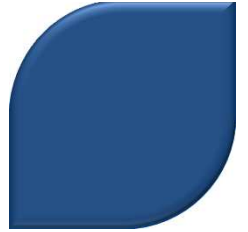
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- ◆ Define a Response Surface Model



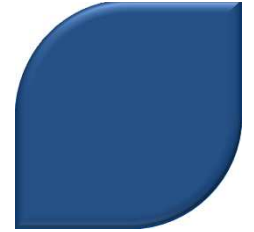
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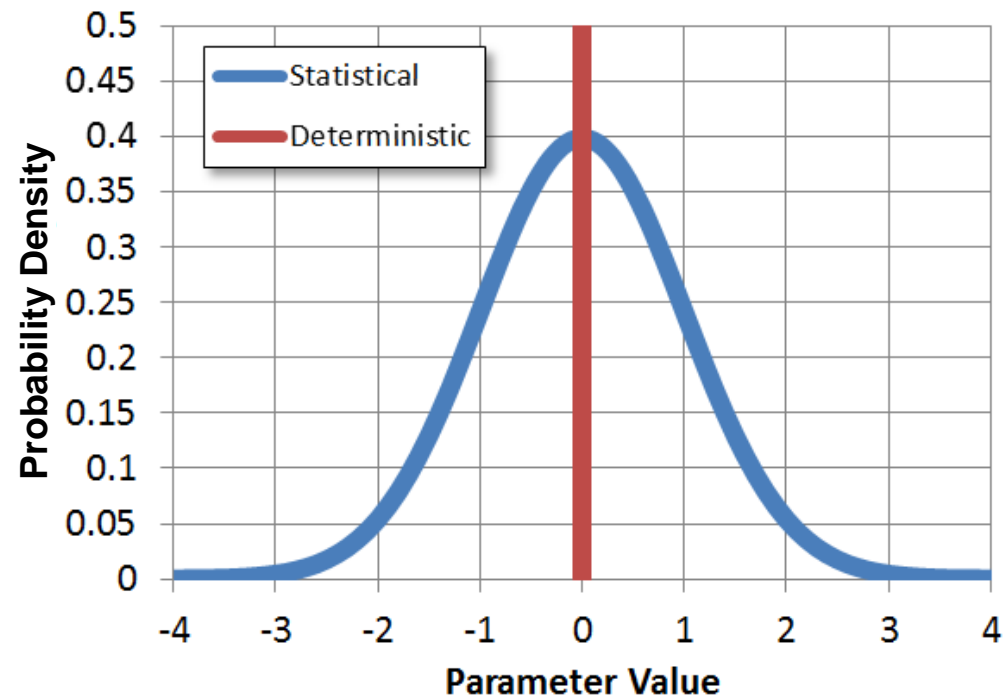
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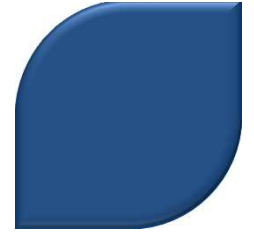
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Deterministic vs. Statistical

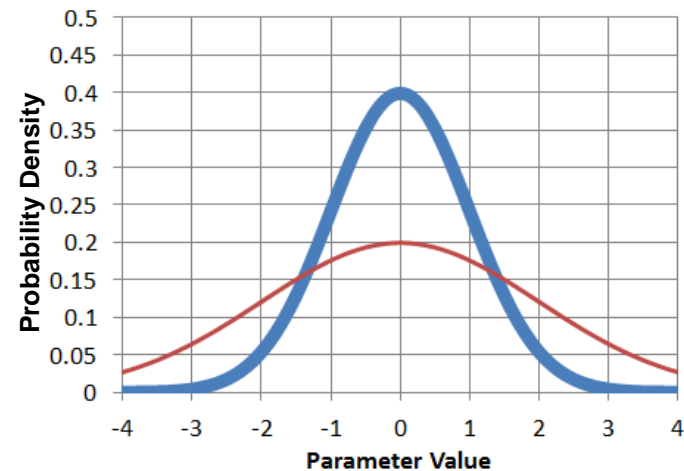
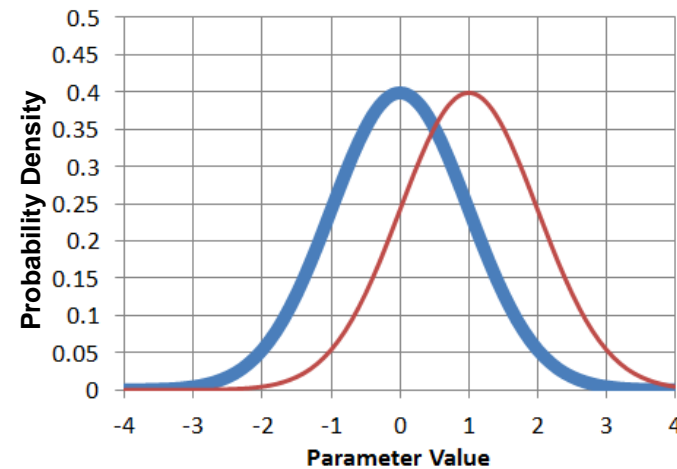
- ▶ **Statistics allows for the treatment of random variability.**
 - ◆ **Deterministic** – Single value used to represent a Parameter.
 - ◆ **Statistical** – Distribution of value used to represent a parameter including random variability.





Types of Uncertainty

- ▶ **Bias** – Shifts the mean of the distribution to the left or to the right
- ▶ **Random** – Impacts the shape of the distribution



Types of Uncertainty

- ▶ A base assumption throughout the setpoint methodology is that uncertainty parameters may be treated as symmetric and normally distributed. **Not always the case in reality**

▶ Example

T_{avg} uncertainty = +4.0F/-4.8F

Bias = -0.4F

Random = +-4.4F

▶ Option 1

- ◆ Apply bounding random uncertainty

Bias = -0.0F

Random = +-4.8F

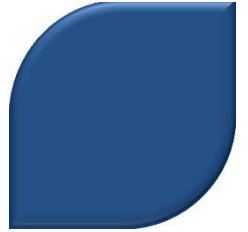
▶ Option 2

- ◆ Apply bias to nominal setting

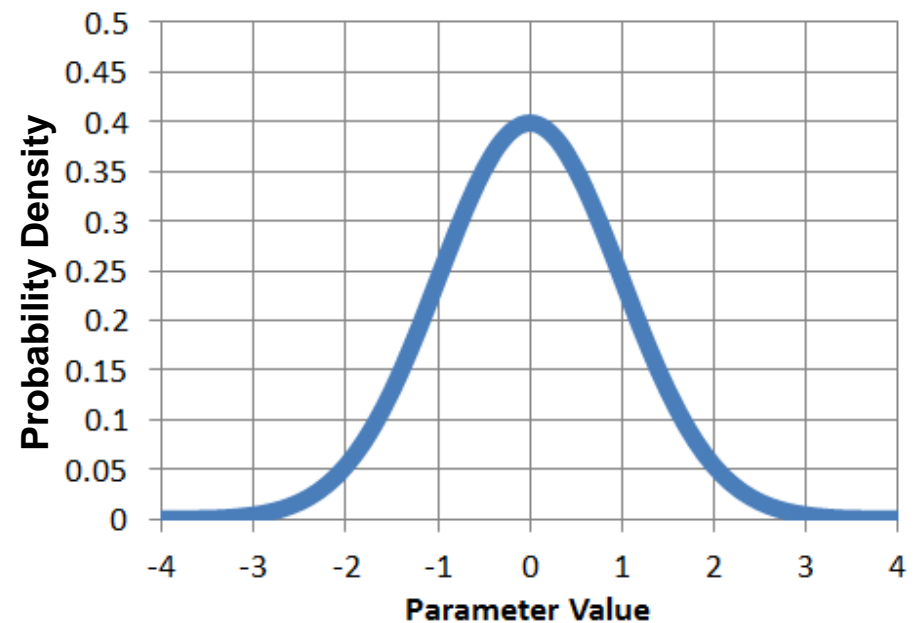
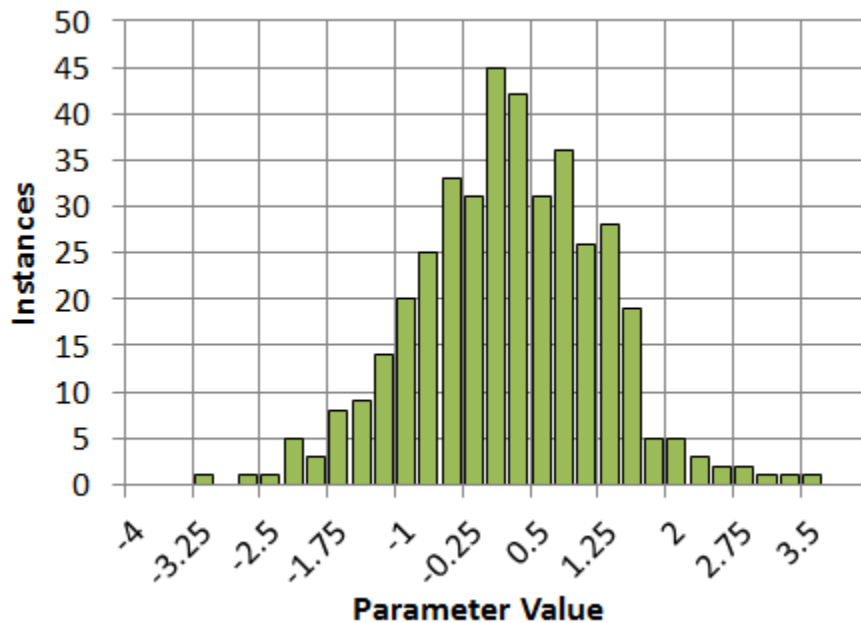
Bias = -0.4F

Random = +-4.4F

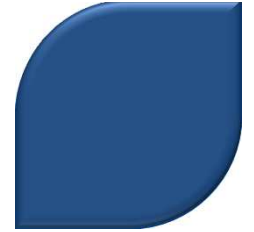
- ▶ Pay extra attention in these situations



- ▶ A Histogram is used to visualize how a collection of data points is distributed.
- ▶ Probability Density Functions (PDF) are often used to analytically estimate statistical distributions.



Review Learning Objectives



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- ◆ Describe the difference between a bias and a random uncertainty

▶ Normal Distribution

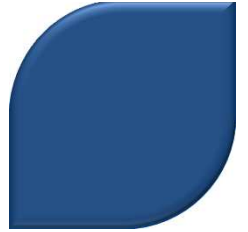
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- ◆ Define a Response Surface Model



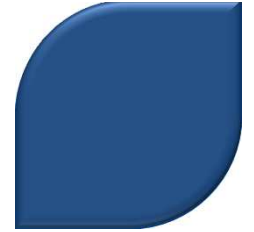
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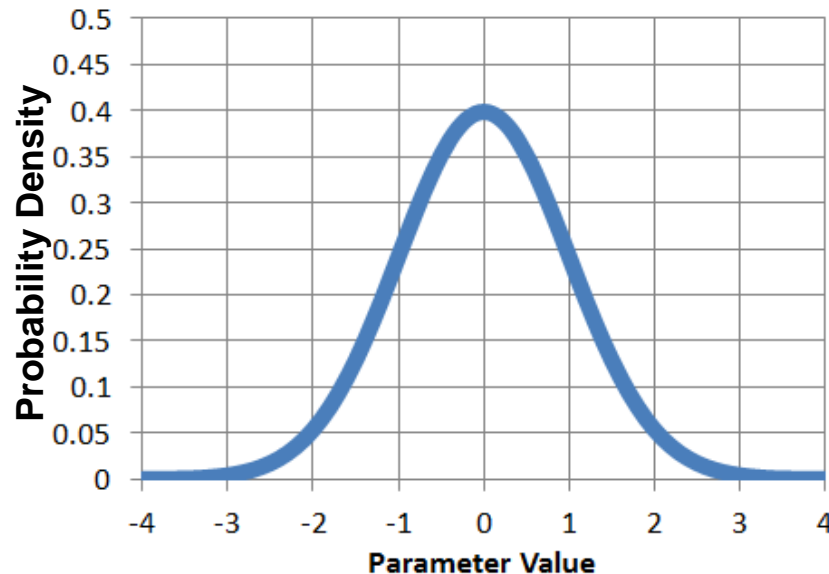
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Normal Distribution

- ▶ Many of the setpoint calculations use probability distributions to model the real world variability in input parameters.
- ▶ Simplified models are typically used.
 - ◆ Most common is a Normal distribution.



$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Where,

μ = mean

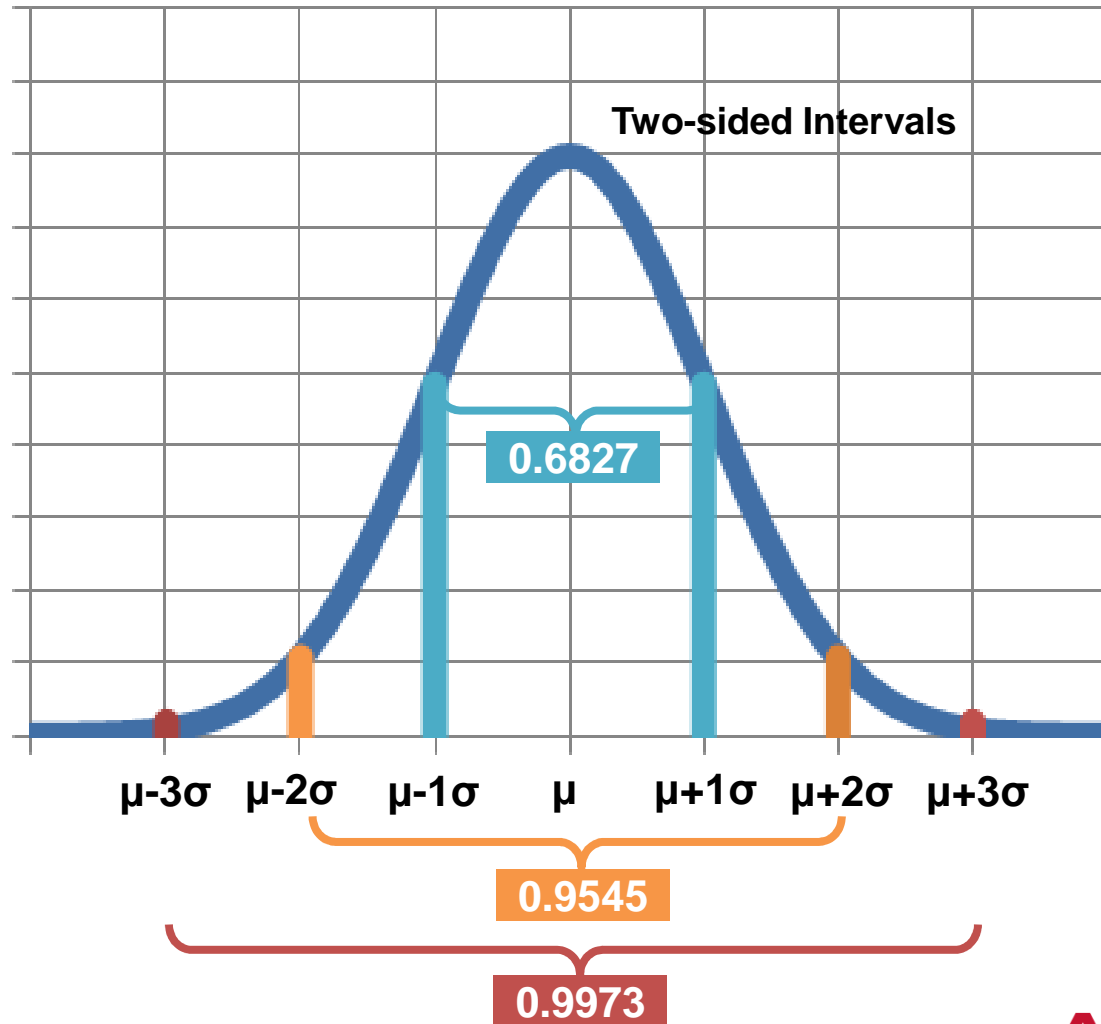
σ = standard deviation

NORMAL DIST.

Normal Distribution

▶ A normal curve represents probability as the area under the curve.

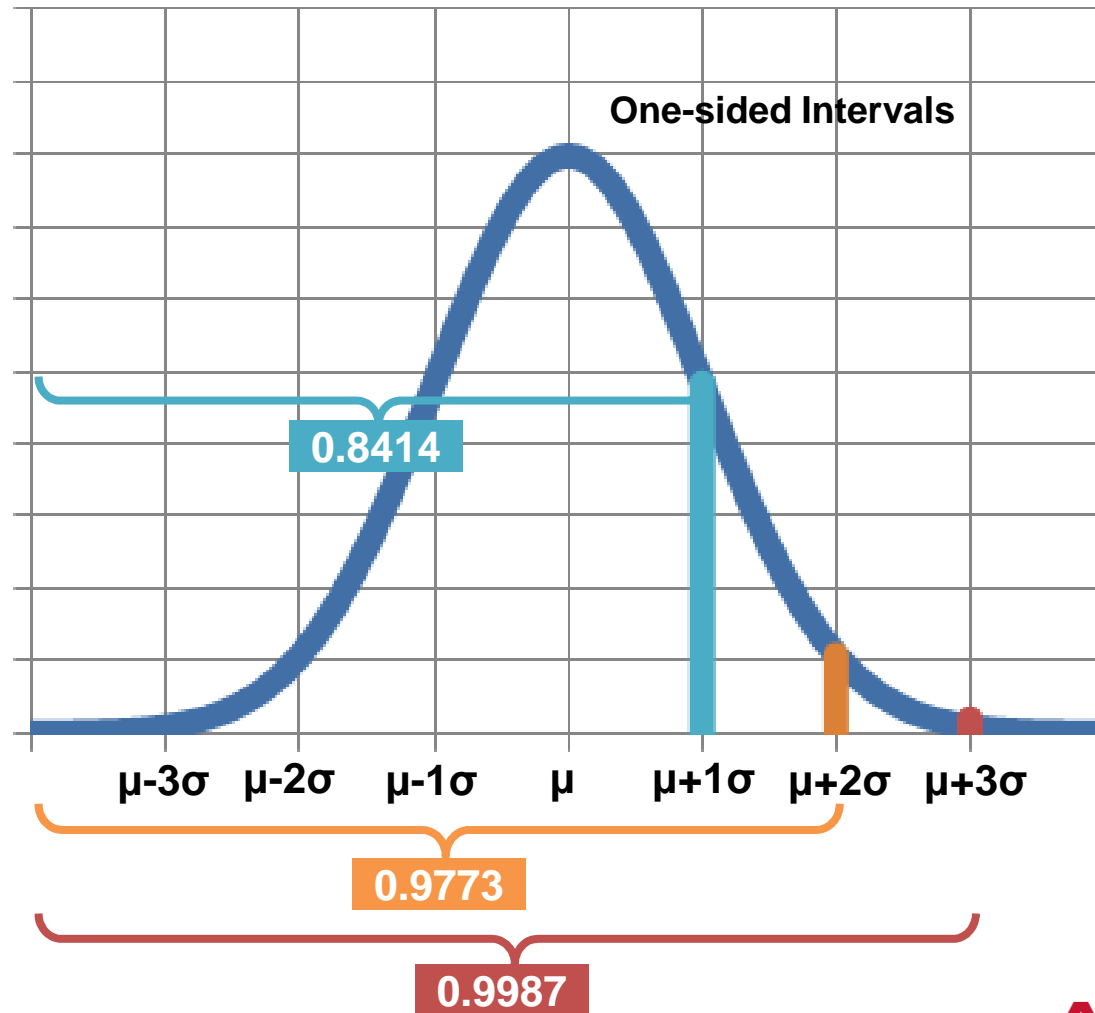
- ◆ Typically calculated using tables because there is not a closed form solution for the integral.
- ◆ Student's T distribution
- ◆ Note that the 2-sigma interval covers just over 95% of the data.



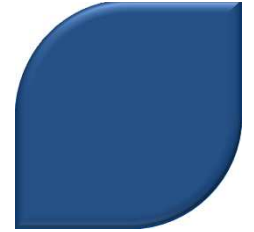
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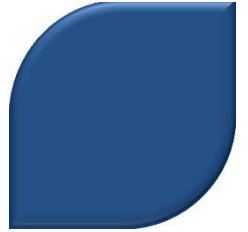
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Tolerance Interval

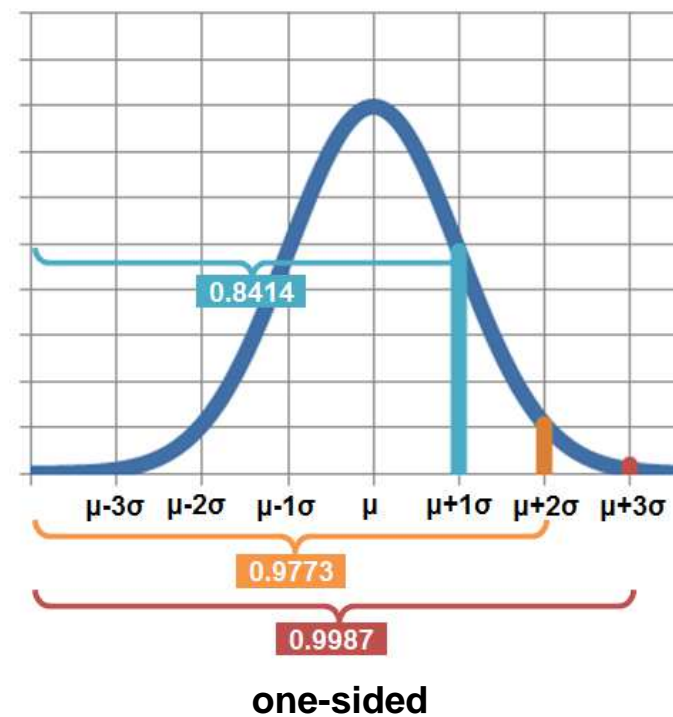
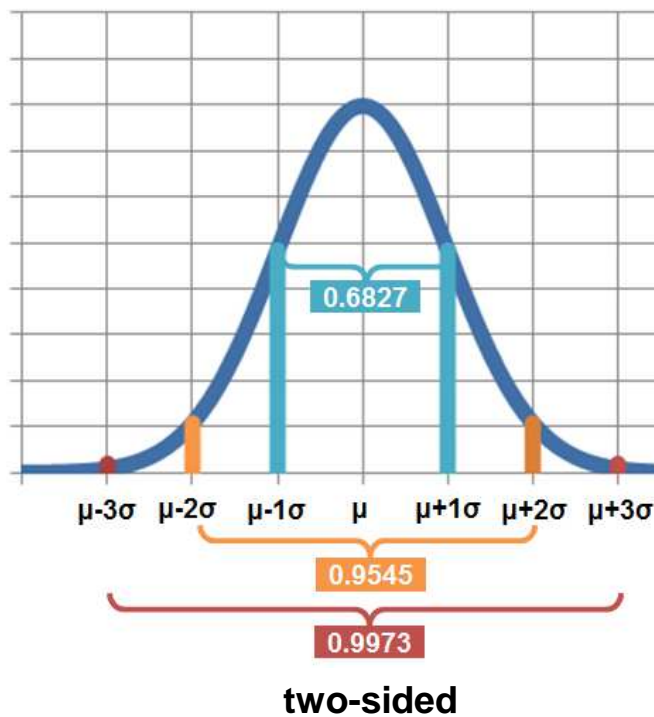
- ▶ A finite data set is inadequate to characterize a parameter's variability with 100% certainty.
- ▶ A tolerance interval has two numbers associated with it, namely a confidence level and a coverage level.
- ▶ The interval is made so that we can have specified confidence that at least the specified portion of the entire population is covered by the interval.
- ▶ For example, a 99/95 tolerance interval means that there is 99% confidence that 95% of the population will be covered by the given interval.
 - ◆ The order of the terms is not always treated consistently (i.e. 99/95 vs. 95/99).
 - ◆ Luckily, we usually use 95/95 so it does not matter.

Tolerance Interval

- ▶ For example, a 99/95 tolerance interval means that there is 99% confidence that 95% of the population will be covered by the given interval.
- ▶ The 99% refers to the confidence of the interval.
- ▶ This is typically impacted by the number of samples available.
 - ◆ A large uncertainty factor must be applied if a small number of samples is available or if a high confidence is desired.
 - ◆ A small uncertainty factor can be applied if a large number of samples is available or if a low confidence is desired.
 - ◆ The confidence of a best estimate calculation is 50%.

Tolerance Interval

- ▶ The 95% is the portion of the population being covered.
- ▶ Coverage can be one-sided or two-sided.



Tolerance Interval

- ▶ Tolerance intervals for normal distributions are of the form:

$$\bar{X} \pm k * s \text{ (two-sided)} \quad \bar{X} - k * s \text{ (lower)} \quad \bar{X} + k * s \text{ (upper)}$$

- ▶ The constants k are typically referred to as “k-factors” and are tabulated.
- ▶ The K factor for a two-sided 95/95 tolerance interval with infinite samples is 1.96
- ▶ The K factor for a one-sided 95/95 tolerance interval with infinite samples is 1.645

\bar{X} (is the sample population mean)

s (is the sample population standard deviation)

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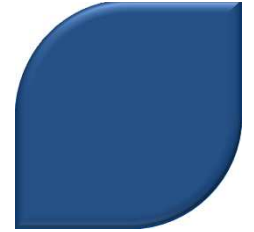
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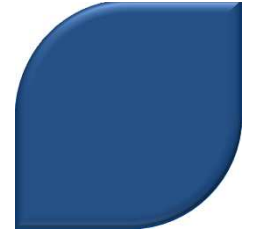
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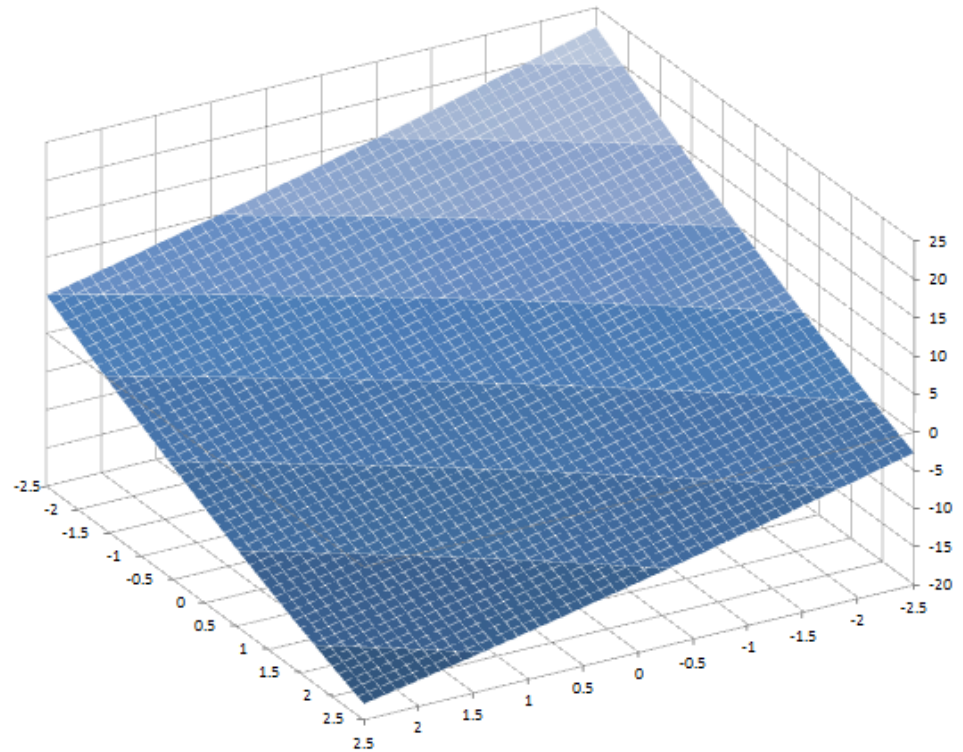
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RSM

Response Surface Model (RSM)

- ▶ A response surface is a multi-dimensional fit of a particular response to a set of input parameters.
- ▶ Typically used to estimate complex phenomenon in an efficient way.



RSM

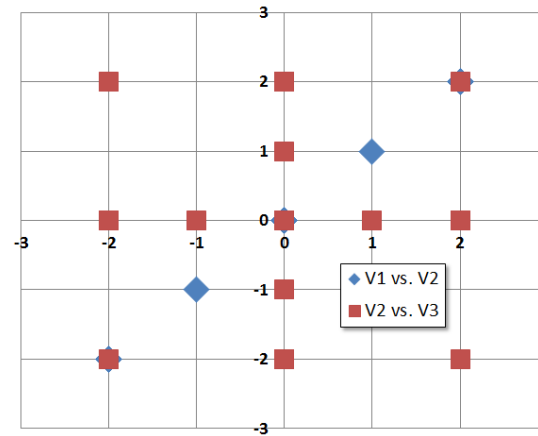
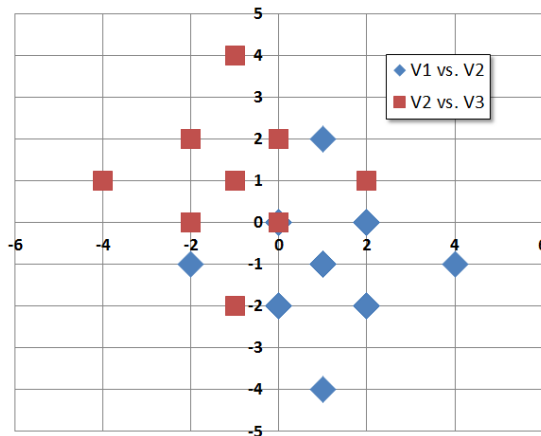
Response Surface Model

- ▶ **To develop an RSM, a set of experimental results characterizing the design space is required.**
 - ◆ For DNBR calculation, the experiments are explicit XCOBRA-IIIC runs
 - ◆ The design space is defined by the min and max of each input parameter
 - ◆ Typically inputs are varied at integer multiples of their standard deviation
- ▶ **One option is to evaluate all possible combinations of each parameter at a given set of levels.**
 - ◆ For example, assume each parameter can be at -2σ , -1σ , 0σ , 1σ , or 2σ
 - ◆ Running all combinations of 10 parameters at 5 levels results in 9,765,625 XCOBRA-IIIC runs

Response Surface Model

► Design of Experiments (DOE)

- ◆ A design of experiments can be used to limit the number of explicit runs needed to build an RSM while minimizing the loss of information
- ◆ Many types of DOE exist
 - Box-Benkhken design
 - Plackett-Burman
 - Cubic centered design



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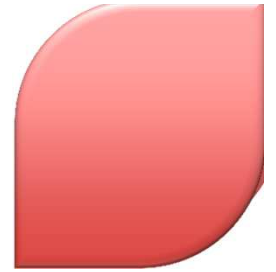
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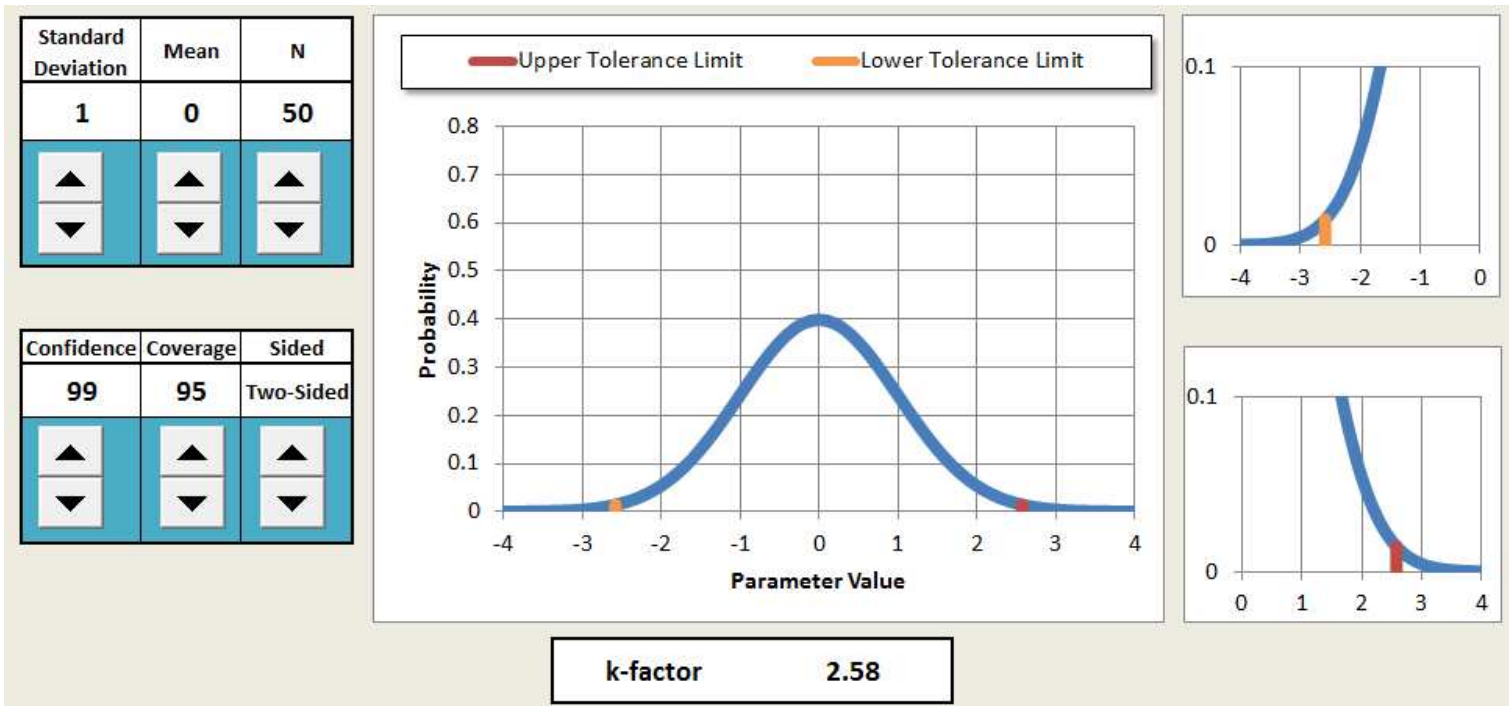
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Exercise 2.1

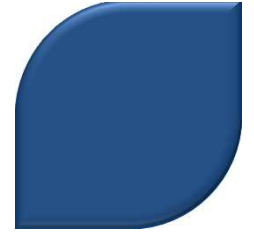


► Companion Notebook > Statistics Tab > Exercise 2.1

◆ Tolerance Intervals



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